

A solution for scatter estimation problem in simultaneous reconstruction, and its impact on deep learning based attenuation correction

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Objectives: In our previous works, a deep learning-based μ -map generation approach using maximum likelihood reconstruction of activity and attenuation (MLAA) was proposed, showing only attenuation correction (AC) error of about 2% compared to CT AC. However, there is a chicken-egg dilemma of scatter estimation. Scatter events are required for conducting MLAA, but estimating scatter events requires μ -maps. To address this issue, the scatter events were derived from CT μ -maps (μ -CT) and assumed to be known in the previous works, which was a crucial limitation. The aim of this study was to solve the scatter estimation problem in MLAA and validate this approach.

Methods: Hundred oncologic patients underwent whole-body F-18-FDG PET scans using a Siemens Biograph mCT 40 scanner. The cases were divided into training (N=60), validating (N=20), and testing (N=20) sets. All data sets were reconstructed using non-attenuation corrected (NAC) OSEM with TOF information. A network (CNN1) based on 3D U-net architecture was employed to generate μ -maps (μ -CNN1) from NAC activity images (λ -NAC). From this μ -map, scatter events were estimated using single scatter simulation (SSS) with the assumption that scatter estimation from μ -CNN1 may not lead to significant errors as the scatter distribution is blurry spread and gradually varying. With this estimated scatter, activity and attenuation maps were obtained using MLAA (λ -, μ -MLAA) with TOF information. Then, a more improved attenuation map was generated by networks using either λ -NAC and/or λ -, μ -MLAA (CNN2 and CNN3, respectively). To validate scatter estimation accuracy, errors in scatter distributions and attenuation coefficient factor (ACF) between μ -CNN1 and μ -CT were measured. To evaluate the accuracy of network-generated μ -maps (μ -CNNs), normalized root-mean-square error (NRMSE) of μ -maps relative to μ -CT were measured. Also, to assess the reliability of AC, we compared the activity images reconstructed using OSEM with TOF information for each μ -CNN using SUV of lung lesions. In addition, we calculated the voxel-wise correlation with CT, not only for μ -maps but also for activity images reconstructed using OSEM with the corresponding μ -maps.

Results: The mean squared error of ACF was over 10% ($10.8\% \pm 2.5\%$), but the mean squared error of scatter distribution was only 3% ($3.2\% \pm 0.1\%$), compared to CT-derived ones. Some lung lesions in μ -CNN1 were excessively large, which resulted in SUV

overestimation. On the other hand, CNN2 that employed scatter estimation from CNN1 generated μ -maps more similar to μ -CT. With aid of NAC input, CNN3 generated μ -maps with better bone identification and lower NRMSE than other μ -CNNs (CNN1: 0.050 ± 0.014 , CNN2: 0.032 ± 0.010 , CNN3: 0.031 ± 0.007). In the activity images reconstructed using these μ -CNNs, CNN3 achieved the highest voxel-wise correlation with μ -CT (CNN1: $y=0.91x+0.08$, $R^2=0.77$; CNN2: $y=0.92x+0.07$, $R^2=0.90$; CNN3: $y=0.96x+0.04$, $R^2=0.90$). In SUV quantification of lung lesions, the slope of the linear regression line of CNN1 was almost 1, but the y-intercept was largest with a positive bias. CNN3 showed the best accuracy.

Conclusion: The errors in μ -CNN1 did not propagate to the scatter estimation. Therefore, despite the insufficient accuracy of μ -CNN1, the scatter estimation from μ -CNN1 could be employed for the scatter correction in MLAA, providing a solution to the scatter problem. Moreover, the NAC approach allows further improvement of μ -CNN by incorporating NAC as an input to the network.